

HY-1B/COCTS vicarious calibration

Xianqiang He

Ocean Remote Sensing Group (ORSG)

State Key Laboratory of Satellite Ocean Environment Dynamics (SOED)

Second Institute of Oceanography of SOA, China (SIO/SOA)



China ocean color (HY-1) satellite missions

- HY-1A Satellite (May 2002- Apr. 2004)
- HY-1B Satellite (Apr. 2007)
- HY-1C/1D Satellite constellation (Approved)



Chinese ocean color and temperature scanner (COCTS)

Sensor	HY-1A/COCTS	HY-1B/COCTS
Spatial resolution	1.1km	1.1km
Scan coverage	1400km	3000km
Digitization	10bit/pixel	10bit/pixel

Band	Wavelength (μm)	Referred radiance ($\text{mW}/\text{cm}^2\mu\text{msr}$)	SNR	Saturated radiance ($\text{mW}/\text{cm}^2\mu\text{msr}$)
1	0.402 ~ 0.422	9.10	349	13.94
2	0.433 ~ 0.453	8.41	472	14.49
3	0.480 ~ 0.500	6.56	467	14.59
4	0.510 ~ 0.530	5.46	448	13.86
5	0.555 ~ 0.575	4.57	417	13.89
6	0.660 ~ 0.680	2.46	309	11.95
7	0.740 ~ 0.760	1.61	200	5.0/9.72
8	0.845 ~ 0.885	1.09	327	3.5/6.93
9	10.30 ~ 11.40	0.2K(300K, NE Δ T)		200-320K
10	11.40 ~ 12.50	0.2K(300K, NE Δ T)		200-320K

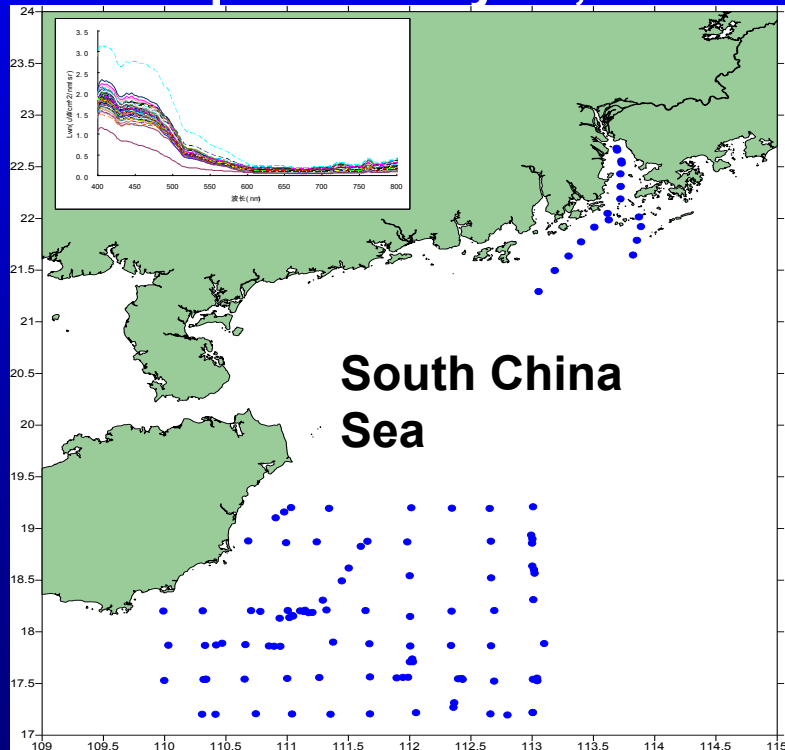
Main challenge

- **No on-orbit calibration device for VIS/NIR.
Difficult to track the degrade of the response.**
- **No pre-launch polarization sensitivity measurement
with whole optic path.**

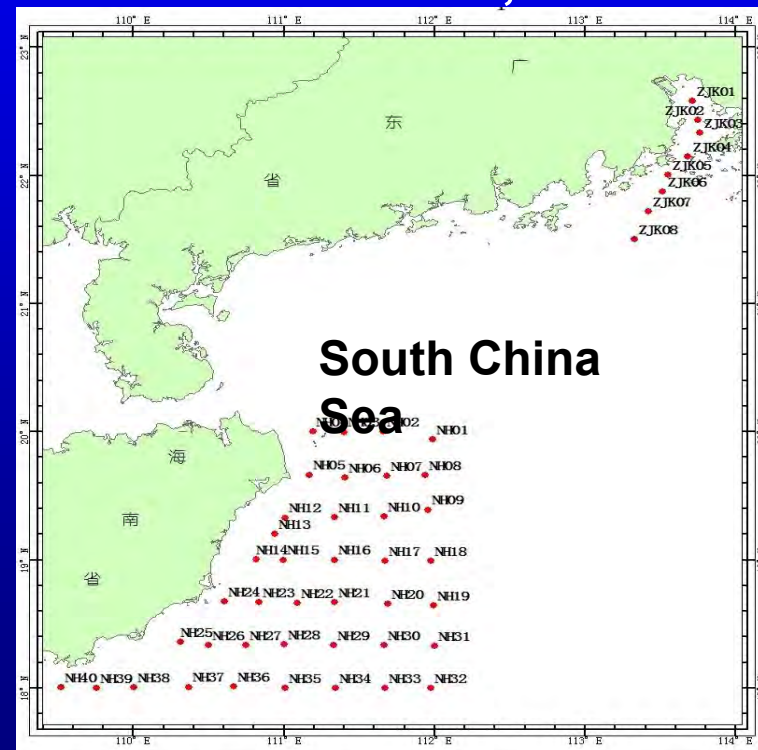
HY-1B/COCTS calibration

- Calibration based on in-situ measurement
- Difficult to carry out frequently, and not suitable for the monitoring of the long-term changes of response.

Apr. 20 - May 15, 2007

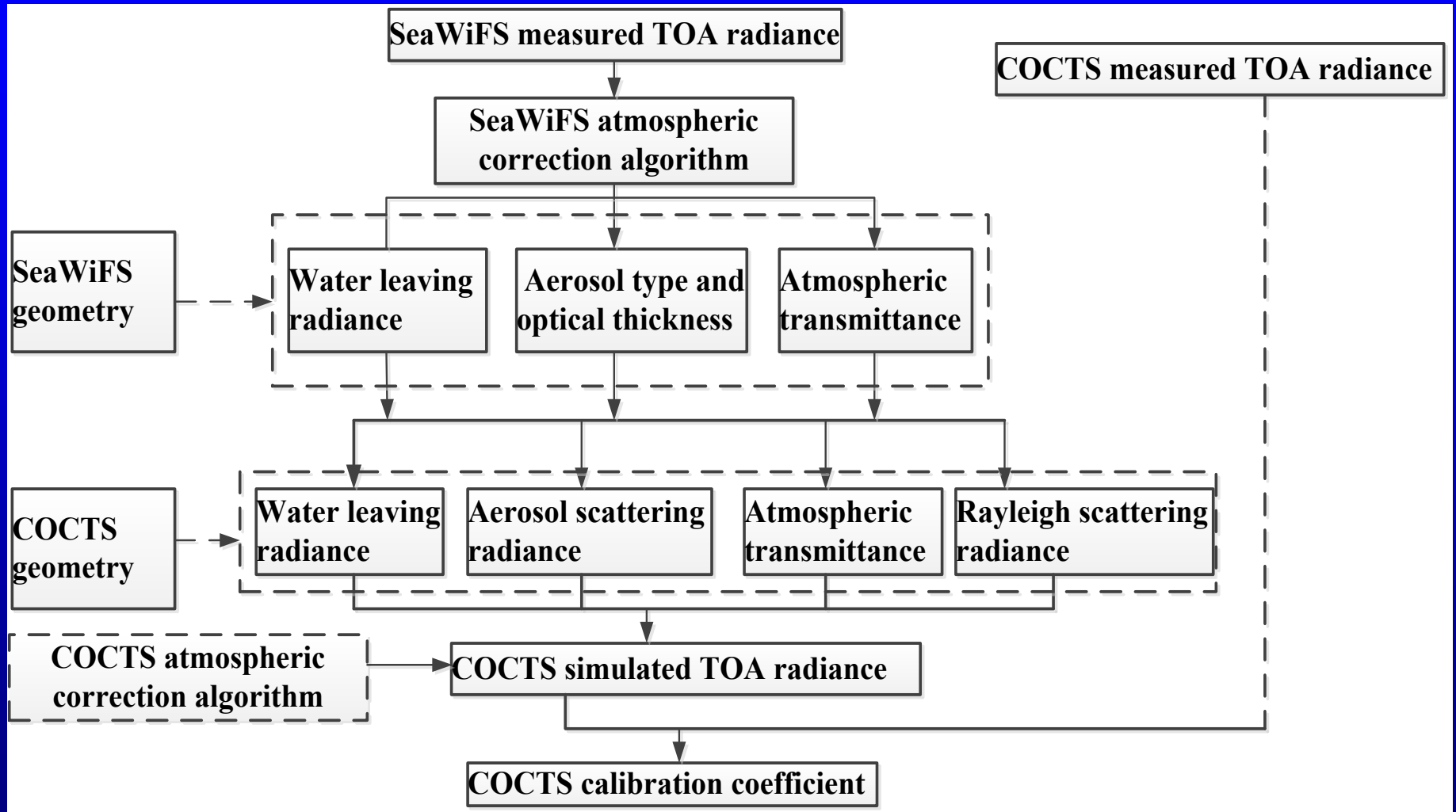


Feb.16 - Mar. 2, 2009



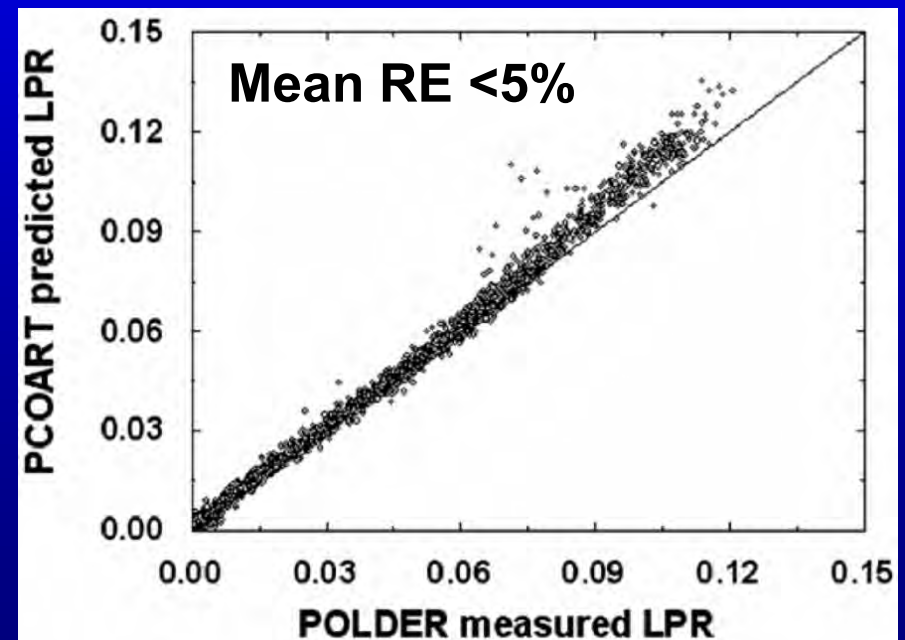
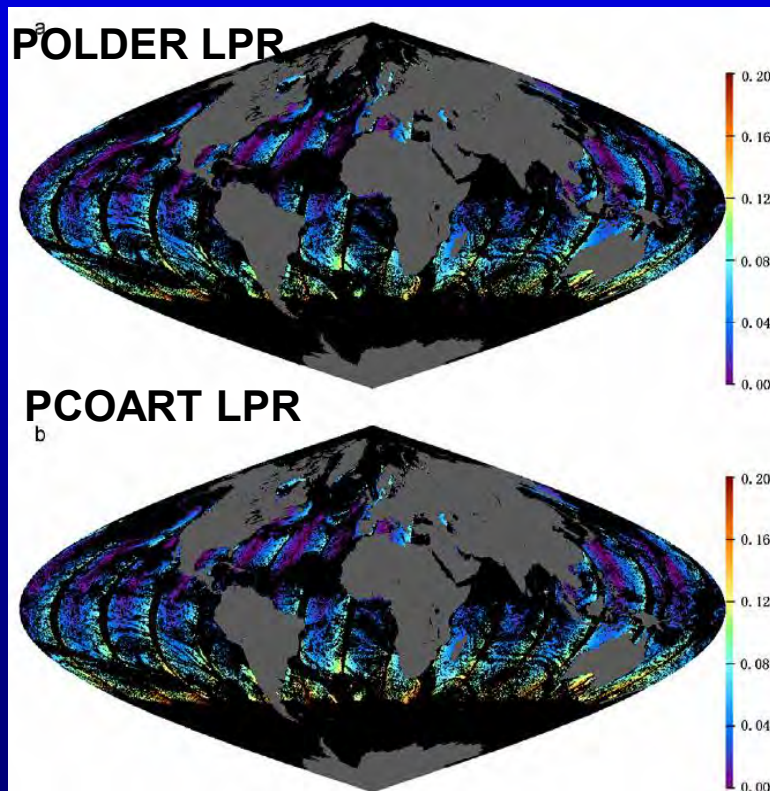
Courtesy of Dr. Qingjun Song from NSOAS, China

Cross-calibration based on SeaWiFS



Atmospheric correction algorithm of HY-1B/COCTS

- Similar as AC algorithm of SeaWiFS/MODIS (Gordon&Wang, 1994).
- A VRT model of coupled ocean-atmosphere system (PCOART) was developed for generation of look-up tables of Rayleigh scattering, aerosol scattering, and atmospheric diffusing transmittance.



He et al., JQSRT, 2010

Aerosol scattering LUT

- Gordon&Wang(1994), SeaWiFS/MODIS/...

$$\ln(L_{ma}) = a + b \ln(L_{as}) + c [\ln(L_{as})]^2$$

- Antoine (1999), MERIS, vector RT model

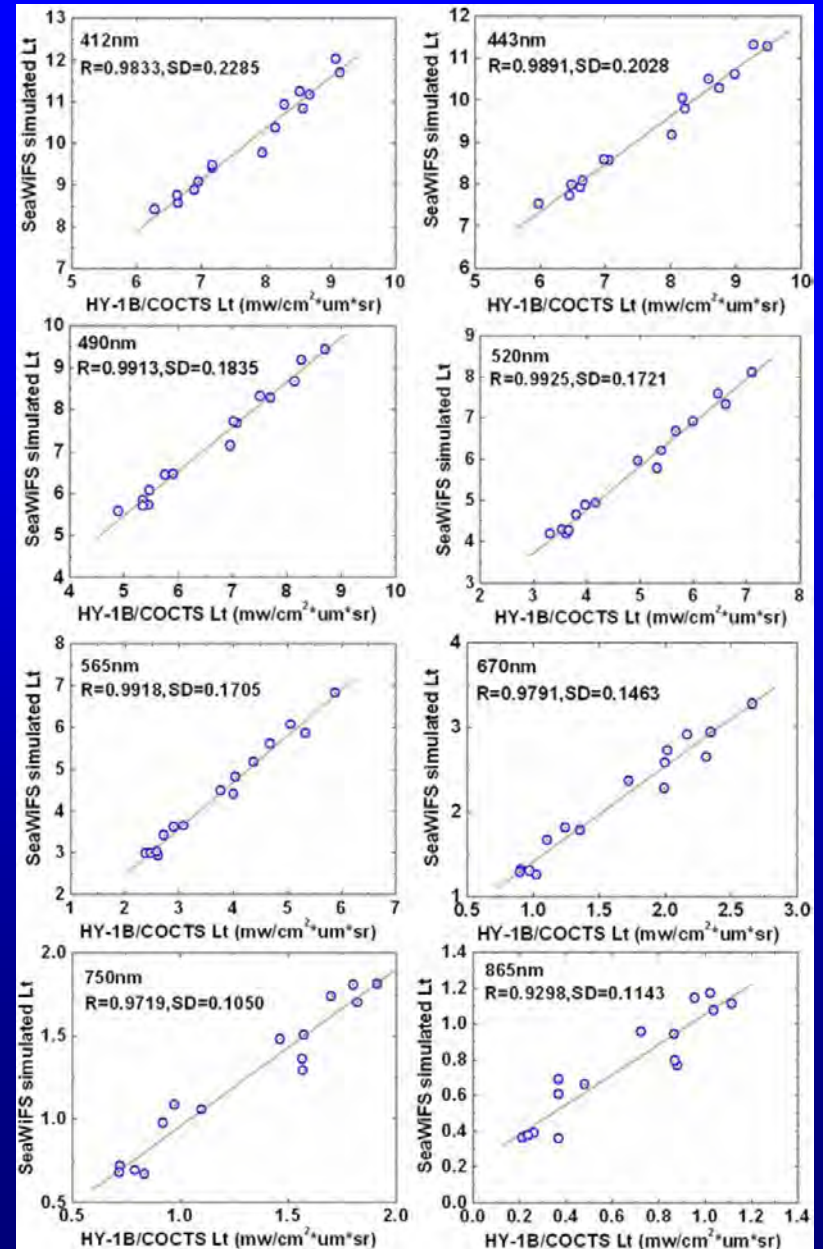
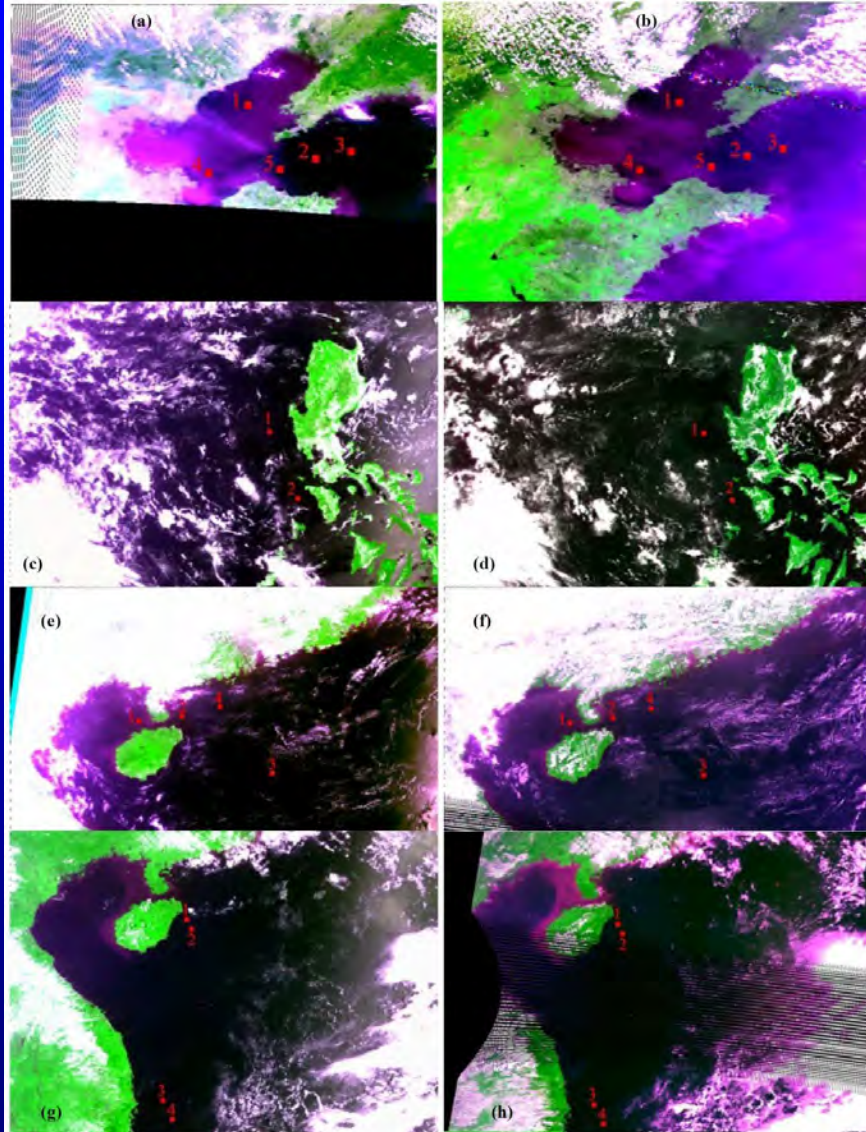
$$\frac{L_{path}}{L_r} = \frac{L_r + L_{ma}}{L_r} = a + b\tau_a + c\tau_a^2$$

- 20 aerosol models were adopted (O98,M98,M90,M80,M70, M50,C98,C90,C80,C70,C50,T98,T90,T80,T70,T50,U98,U90 ,U70,U50).

Cross-calibration of HY-1B/COCTS based on SeaWiFS

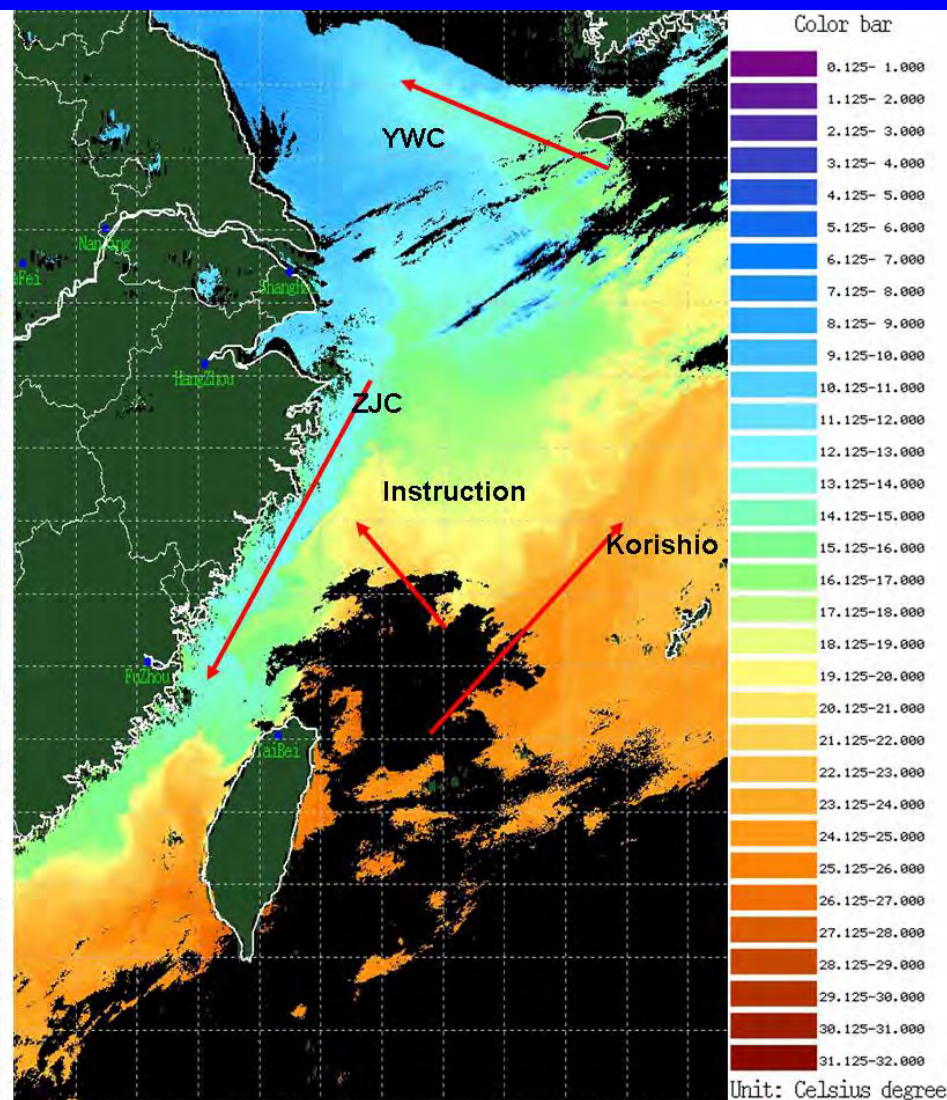
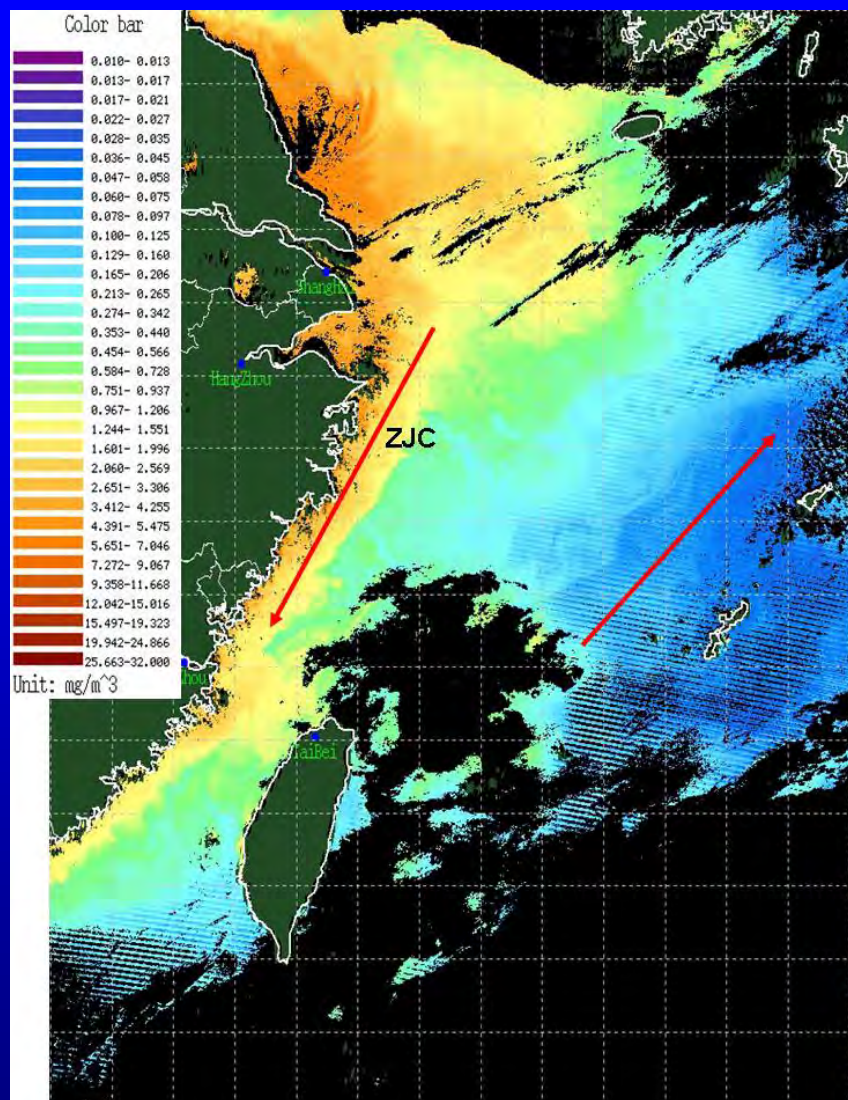
COCTS

SeaWiFS



Chl_a

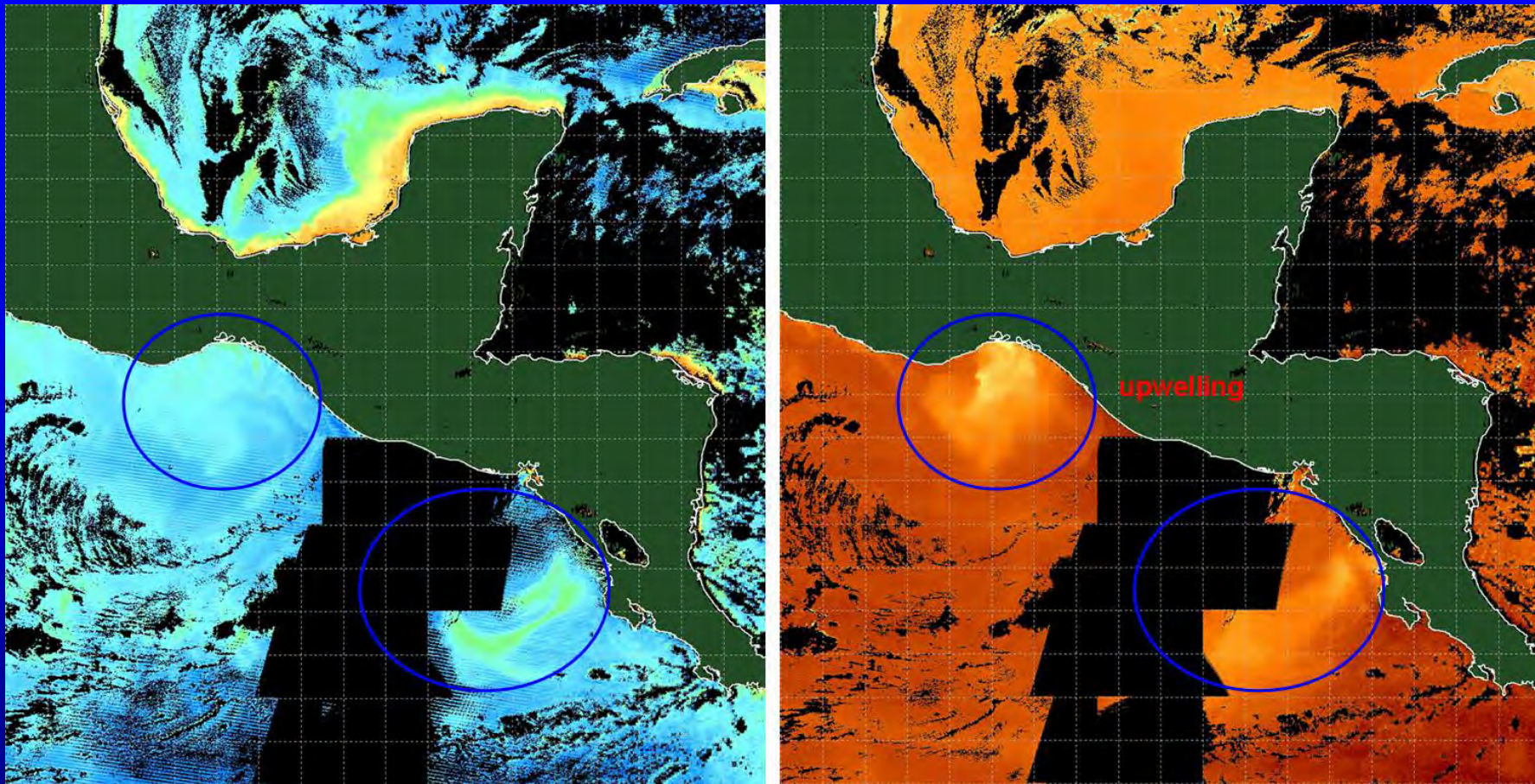
SST



2008-3-2 02:19 GMT

Chl_a

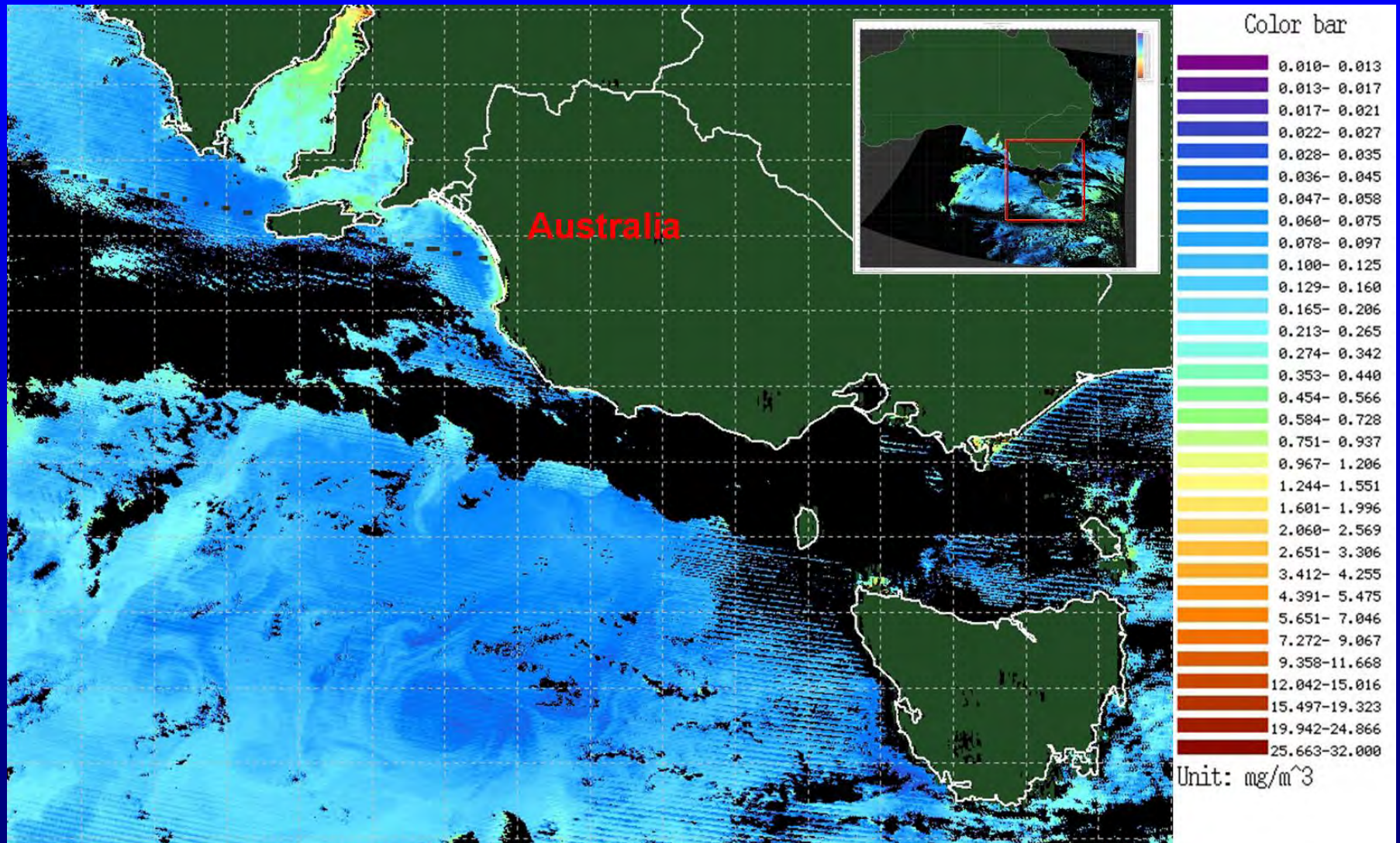
SST



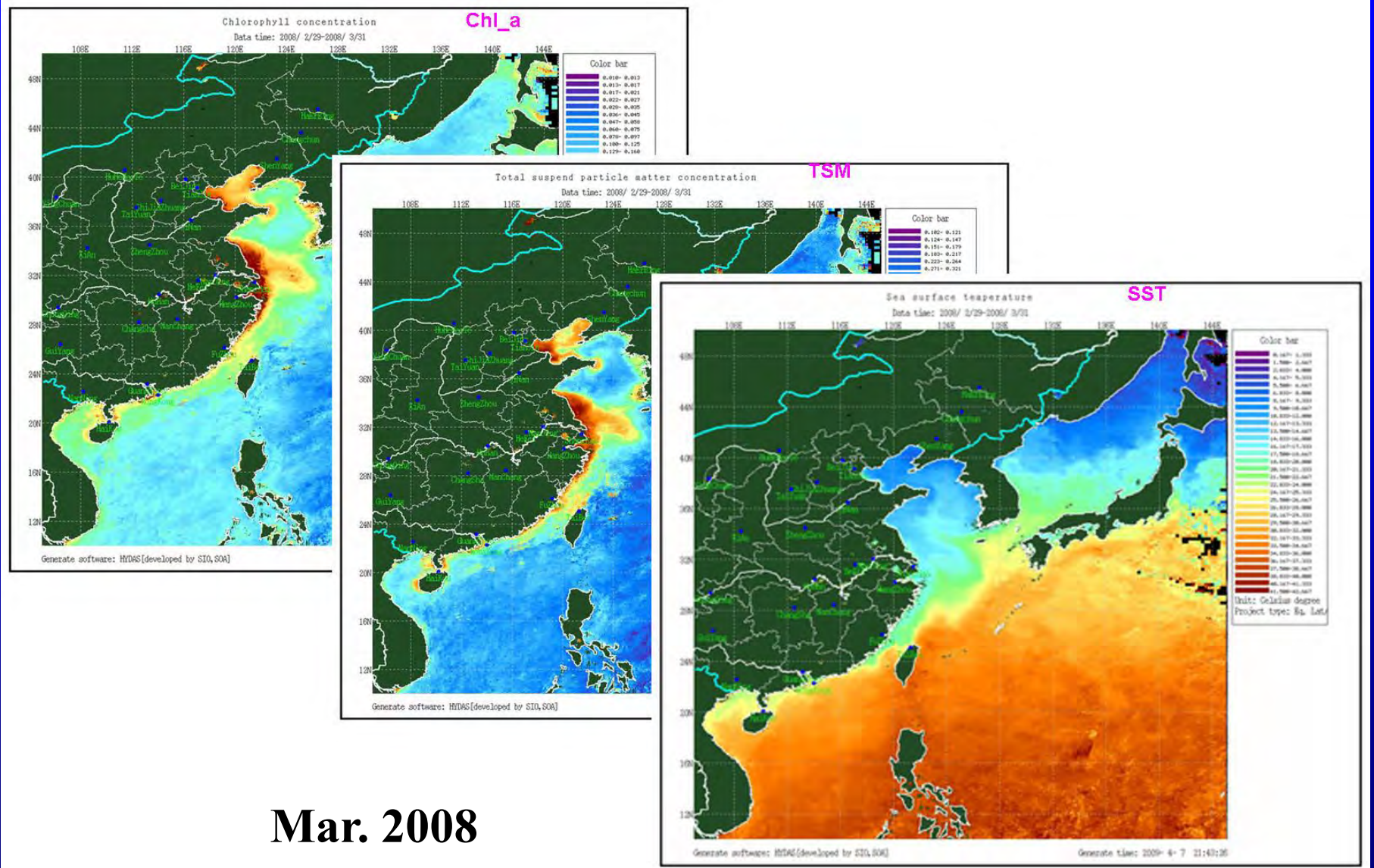
2008-2-29 16:49 GMT

Chlorophyll concentration

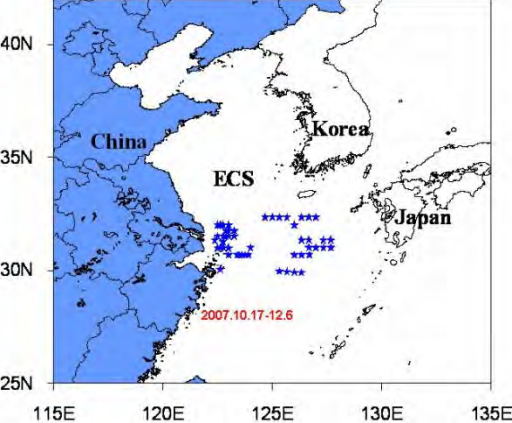
2009-1-26 00:30 GMT



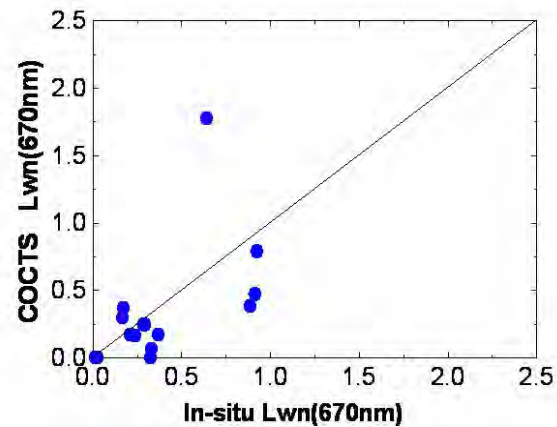
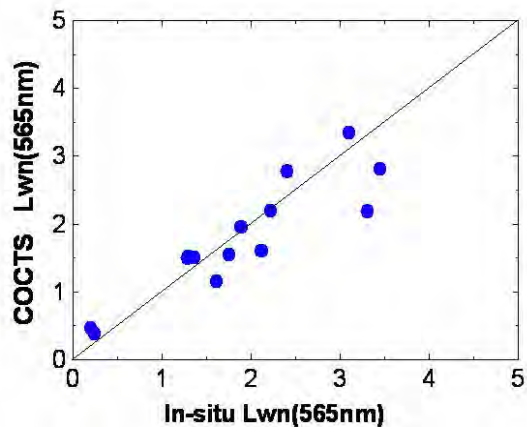
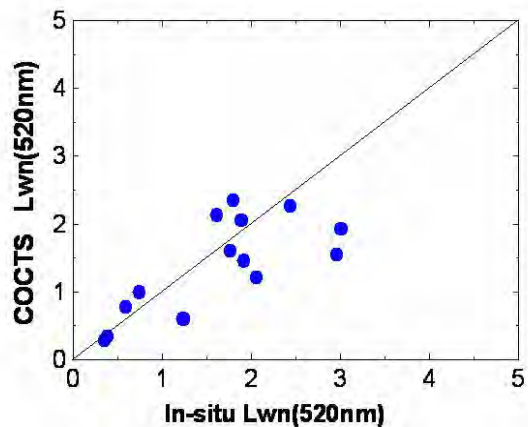
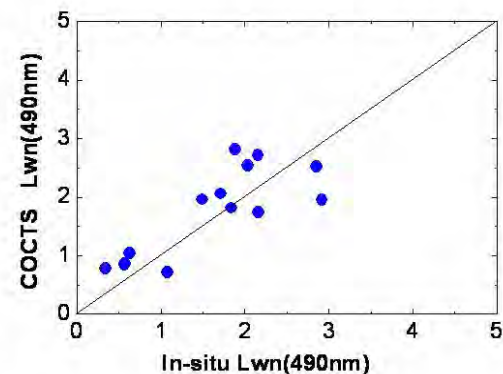
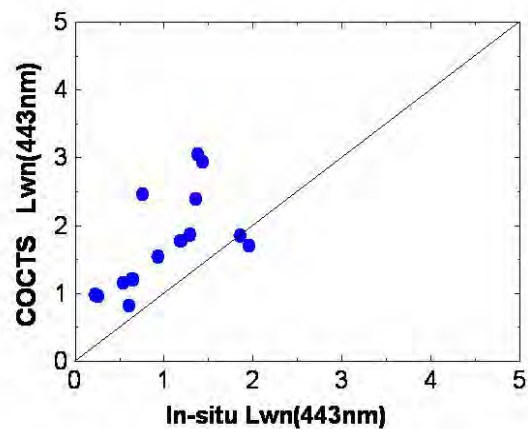
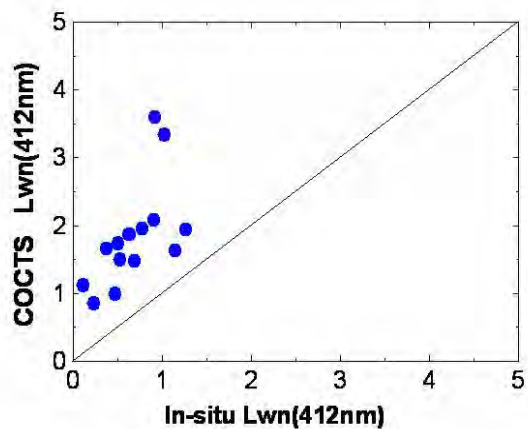
Monthly products



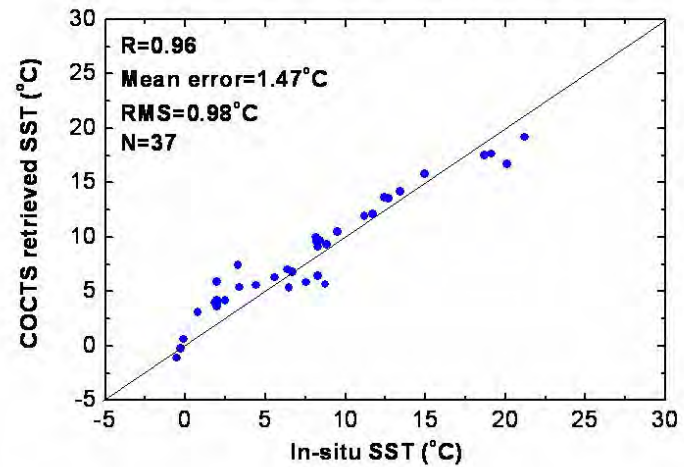
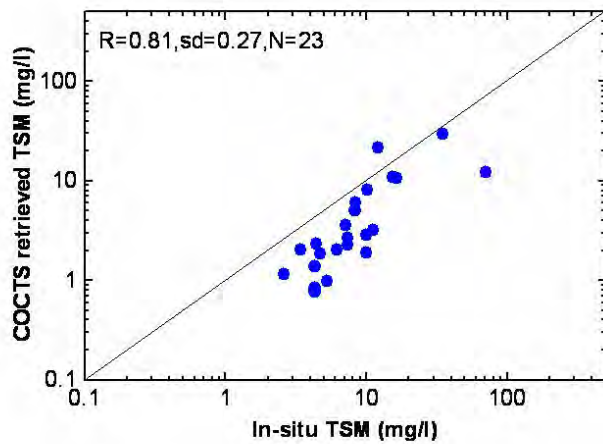
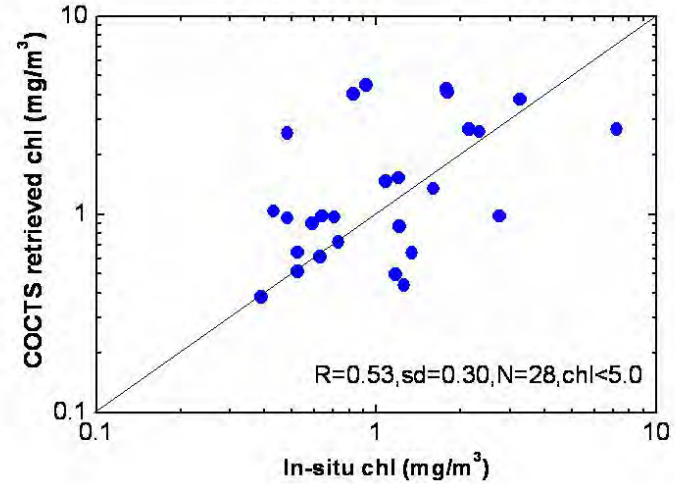
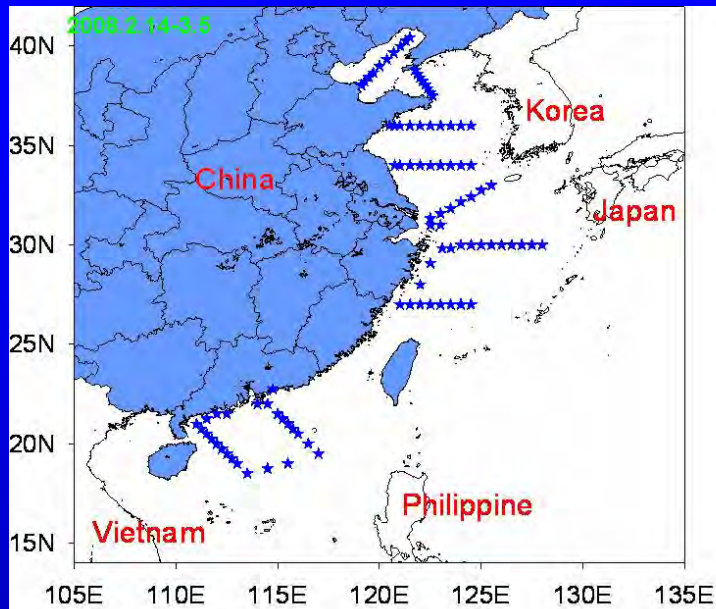
Mar. 2008



Validation of Lwn retrieved by HY-1B/COCTS



Validation of oceanic parameters retrieved by HY-1B/COCTS

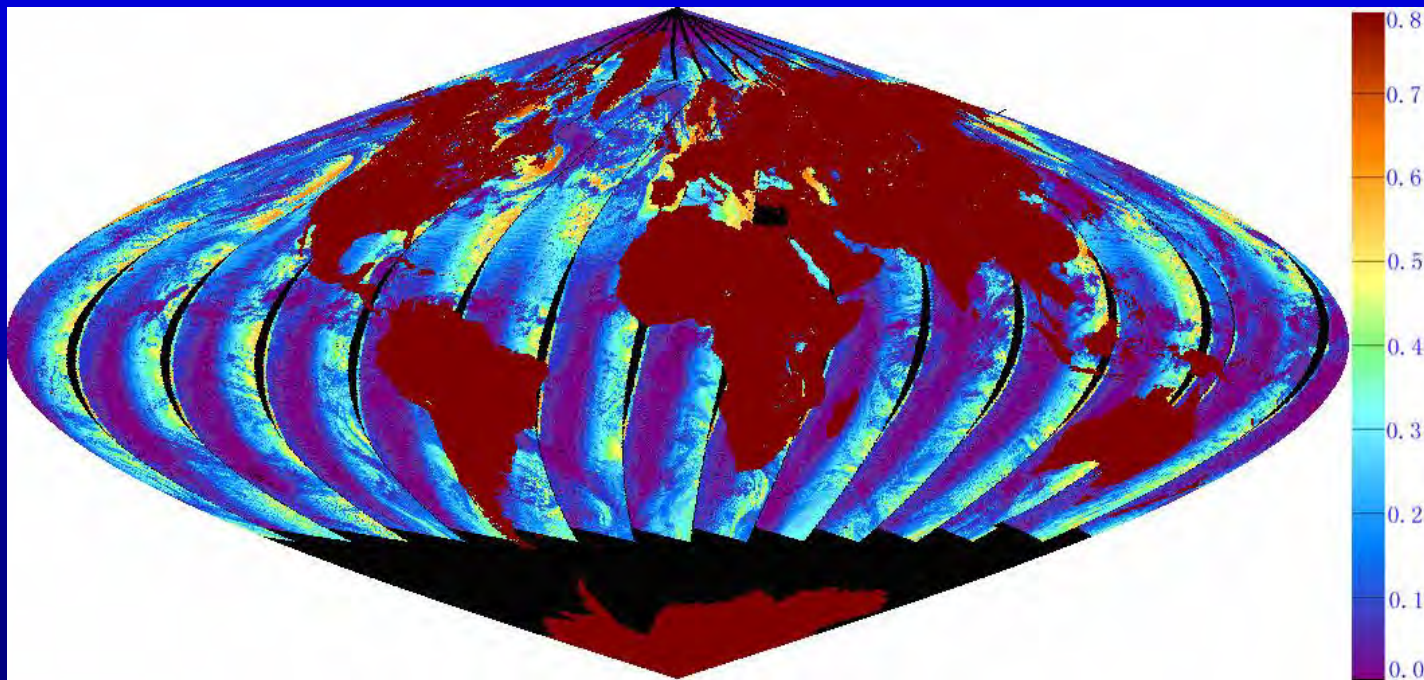


Main challenge

- **No on-orbit calibration device for VIS/NIR.**
Difficult to track the degrade of the response.
- **No pre-launch polarization sensitivity measurement with whole optic path.**

Polarization sensitivity of HY-1B/COCTS

- Design goal: $<5\%$ (within $\pm 20^\circ$), larger than the requirement ($<2.5\%$).
- Polarization can induce 3% error of sensor measured radiance ($0.05 \times 0.7 \times 0.9 = 0.032$), which can induce 30% error of Lwn.



Linear polarization degree at TOA observed by POLDER (2003-7-10)

On-orbit estimation of polarization sensitivity

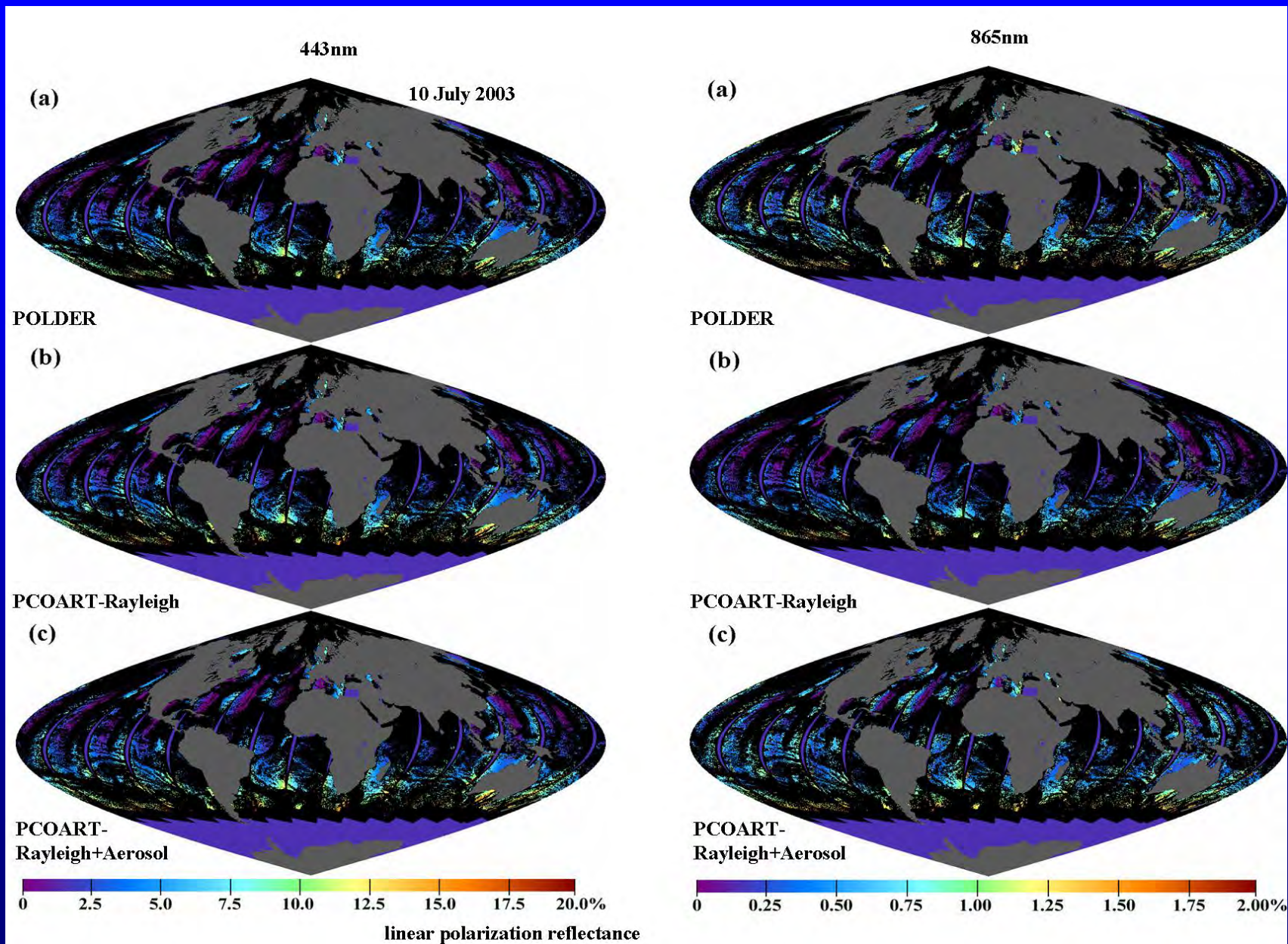
$$I_t(scene) = I_m(scene) \left(1 - \frac{Q_t(scene)}{I_m(scene)} m_{12} - \frac{U_t(scene)}{I_m(scene)} m_{13} \right)$$

$I_t(scene)$ **Exact radiance estimated by cross-calibration using SeaWiFS**

$I_m(scene)$ **Sensor measured radiance**

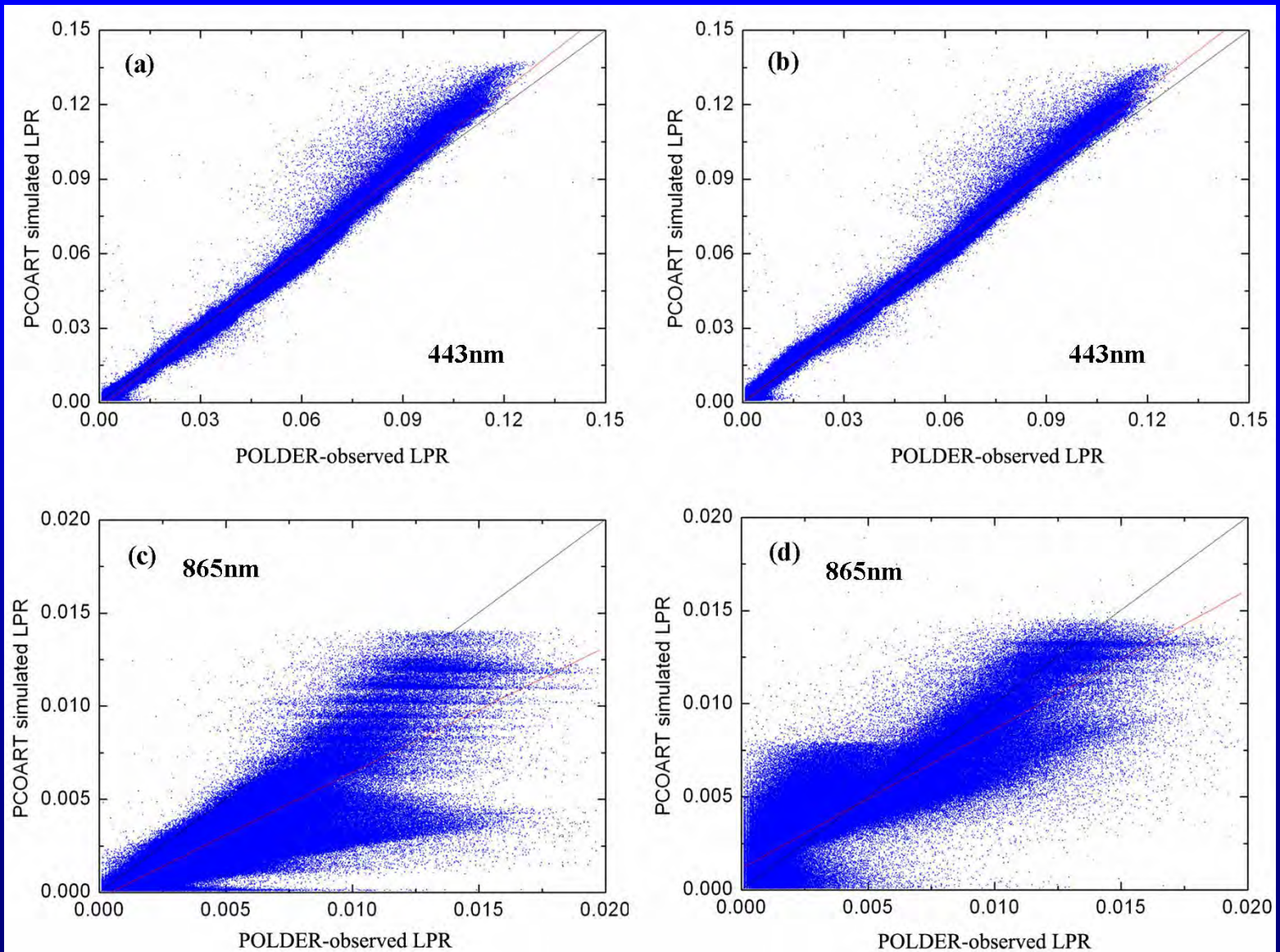
$Q_t(scene), U_t(scene)$ **Simulated by vector RT model (PCOART), including aerosol**

Linear polarization components simulated by VRT

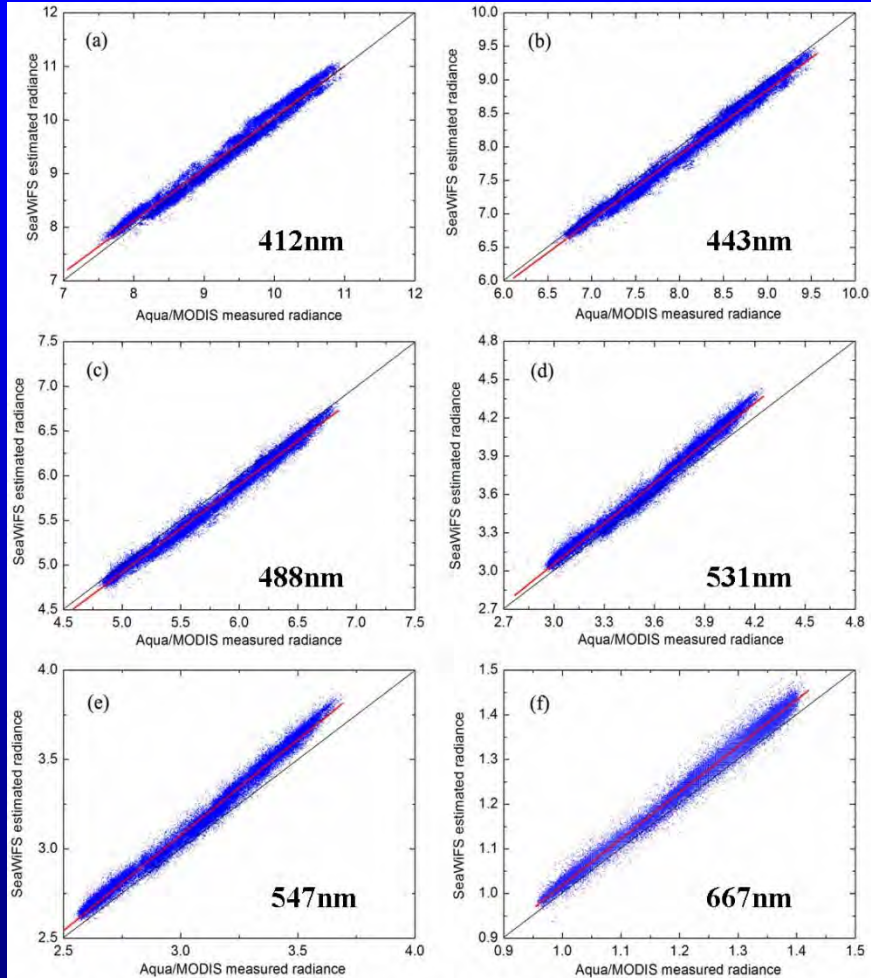


Without aerosol

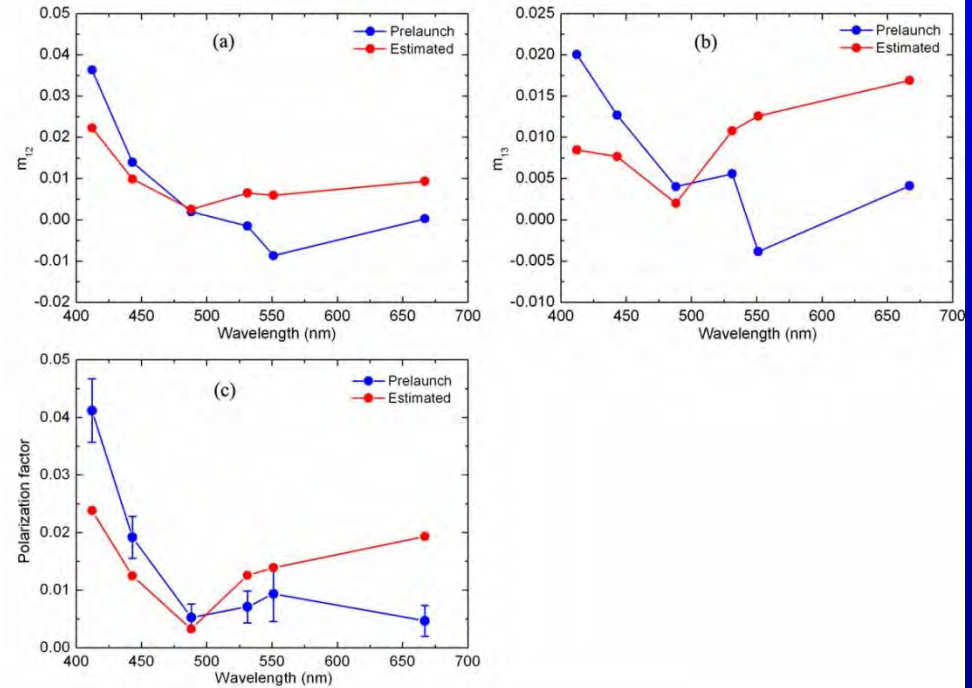
With aerosol



Method test- apply to Aqua/MODIS

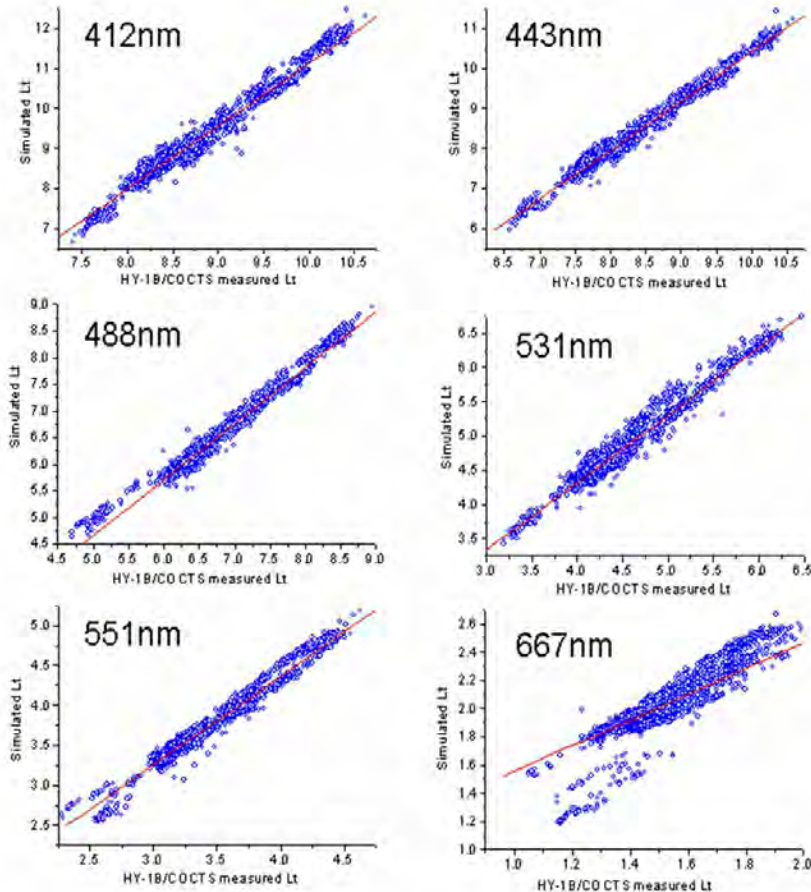


Comparison of estimated and prelaunch polarization responses



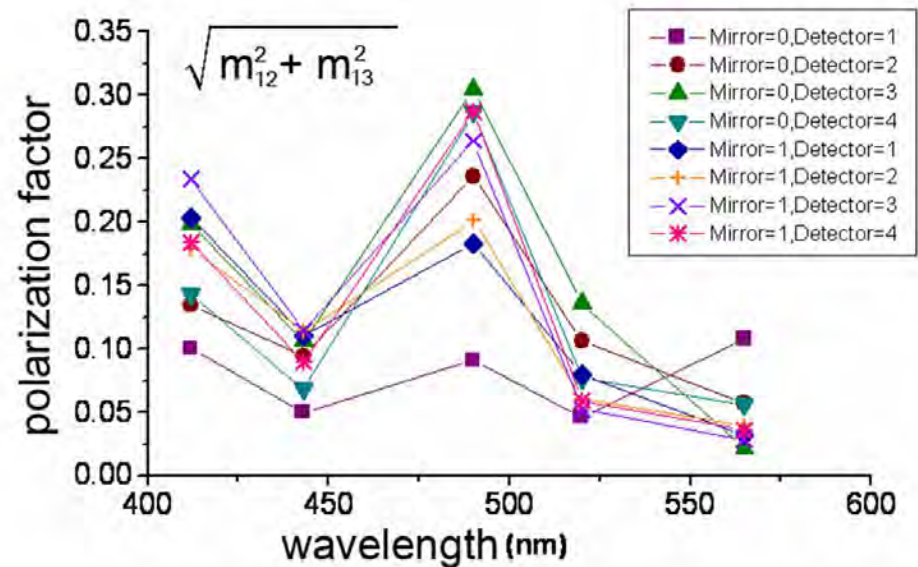
Cross-calibration by SeaWiFS

Method applying to HY-1B/COCTS

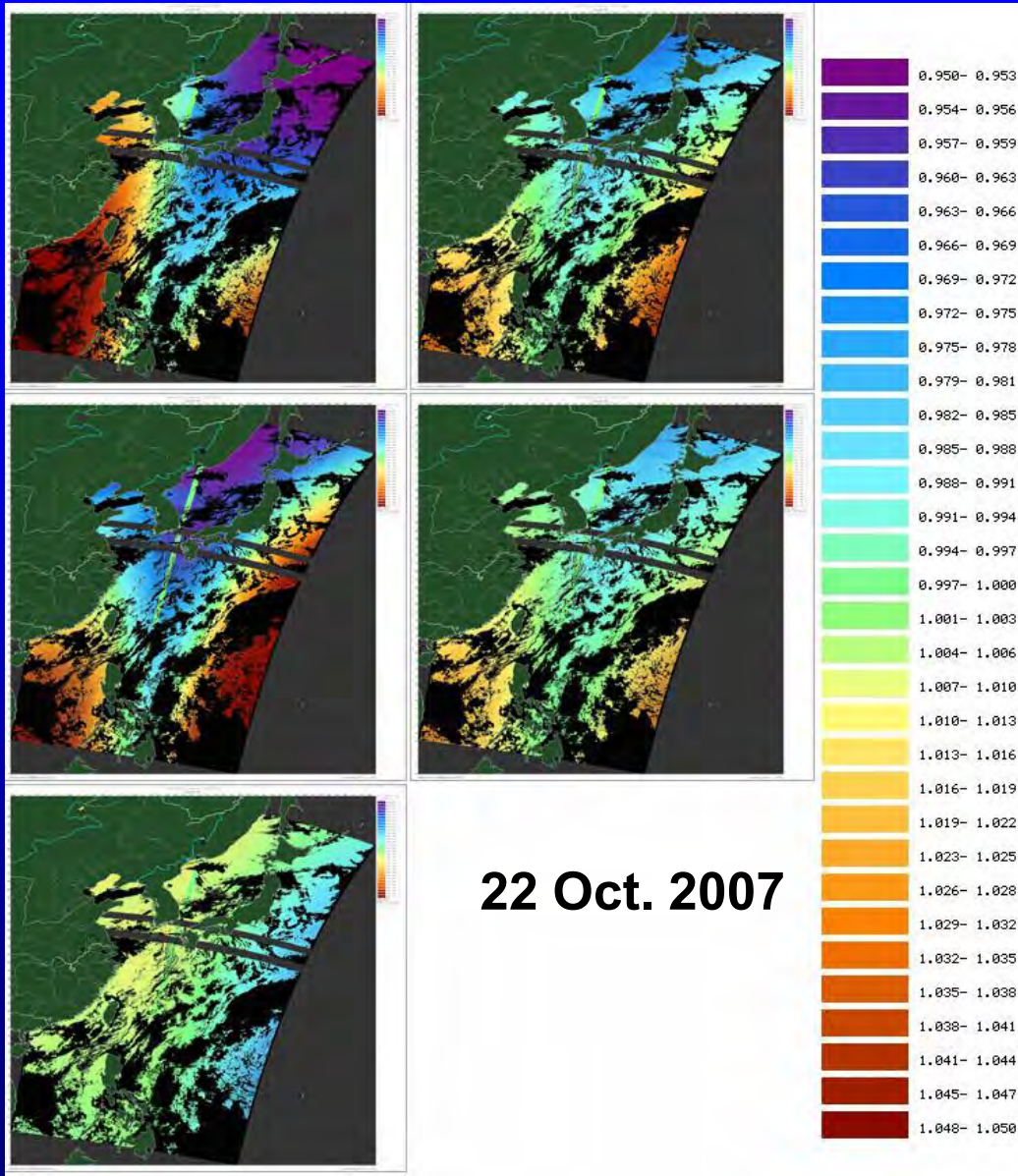


**Cross-calibration by SeaWiFS
(Mirror 0, detector 1)**

Estimated polarization factor

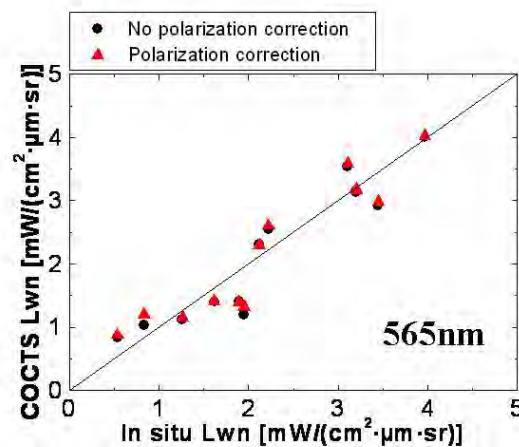
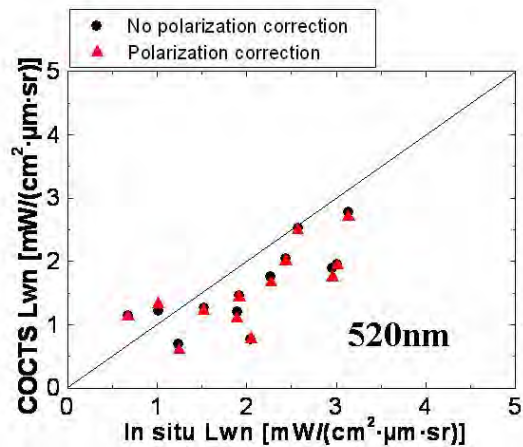
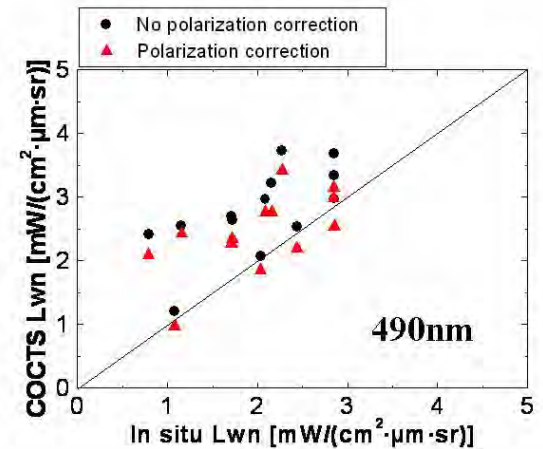
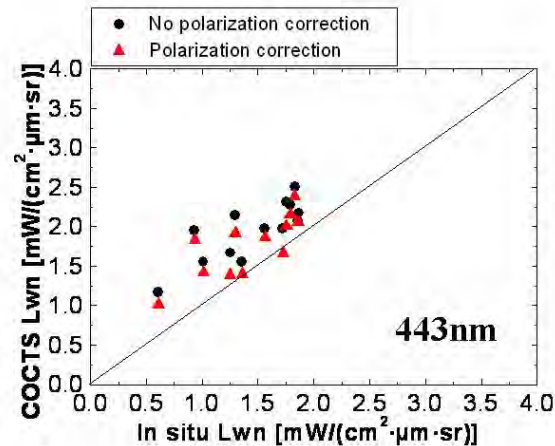
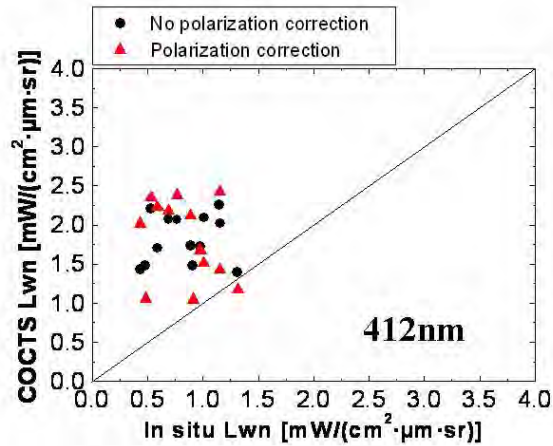


Polarization sensitivity correction



- Large correction at edges, with maximum up to 5%;
- 412nm and 490nm has relative large correction.

Polarization correction improving Lwn retrieval



Summary

- **HY-1B/COCTS has no onboard calibration device and no pre-launch measurement of polarization sensitivity, make it challenge for calibration.**
- **Cross-calibration has been carried out for HY-1B/COCTS based on SeaWiFS. Analysis of long-term change of sensitivity and data reprocess will be done using the Aqua/MODIS in the future.**
- **Polarization sensitivity can be estimated preliminarily based on on-orbit data.**



ORSG

OCEAN REMOTE SENSING GROUP

***Thanks for your
attention !***